

ACME III EDM blinding

**“Inconsistent” blinding  
(For asymmetry)**

# Two “natural” ways to blind

## Blind in parity basis (ACME II and I)

$$\omega_{\text{blinded}}^{\mathcal{N}\mathcal{E}} = \omega^{\mathcal{N}\mathcal{E}} + \omega_{\text{blind}}$$

$$\Phi_{\text{blinded}}^{\mathcal{N}\mathcal{E}} = \Phi^{\mathcal{N}\mathcal{E}} + \omega_{\text{blind}} \tau_j$$

$$\mathcal{A}_{\text{blinded}}^{\mathcal{N}\mathcal{E}} = \mathcal{A}^{\mathcal{N}\mathcal{E}} + 2\mathcal{C}\omega_{\text{blind}} \tau_j$$

$$\mathcal{A}_{\text{blinded}}^{p \neq \mathcal{N}\mathcal{E}} = \mathcal{A}^{p \neq \mathcal{N}\mathcal{E}}$$

## Blind in state basis

$$\omega_{\text{blinded, state}} = \omega_{\text{state}} + \omega_{\text{blind}} \tilde{\mathcal{N}} \tilde{\mathcal{E}}$$

$$\Phi_{\text{blinded, state}} = \Phi_{\text{state}} + \omega_{\text{blind}} \tau_j \tilde{\mathcal{N}} \tilde{\mathcal{E}}$$

$$\mathcal{A}_{\text{blinded, state}} = \mathcal{A}_{\text{state}} + 2\mathcal{C}_{\text{state}} \omega_{\text{blind}} \tau_j \tilde{\mathcal{N}} \tilde{\mathcal{E}}$$

## Blind in state basis, when viewed in parity basis

$$\omega_{\text{blinded}}^{\mathcal{N}\mathcal{E}} = \omega^{\mathcal{N}\mathcal{E}} + \omega_{\text{blind}}$$

$$\Phi_{\text{blinded}}^{\mathcal{N}\mathcal{E}} = \Phi^{\mathcal{N}\mathcal{E}} + \omega_{\text{blind}} \tau_j$$

$$\mathcal{A}_{\text{blinded}}^{\mathcal{N}\mathcal{E}} = \mathcal{A}^{\mathcal{N}\mathcal{E}} + 2\omega_{\text{blind}} \tau_j f^{\mathcal{N}\mathcal{E}}(c^{\text{nr}}, c^{\mathcal{N}}, c^{\mathcal{E}}, c^{\mathcal{B}}, c^{\mathcal{N}\mathcal{E}}, \dots)$$

$$\mathcal{A}_{\text{blinded}}^{p \neq \mathcal{N}\mathcal{E}} = \mathcal{A}^{p \neq \mathcal{N}\mathcal{E}} + 2\omega_{\text{blind}} \tau_j f^{p \neq \mathcal{N}\mathcal{E}}(c^{\text{nr}}, c^{\mathcal{N}}, c^{\mathcal{E}}, c^{\mathcal{B}}, c^{\mathcal{N}\mathcal{E}}, \dots),$$

where  $f$  is some function that depends on the values of the contrasts.

## Example (only E switch):

Say the unblinded data is:

	$\mathcal{C}$	$\mathcal{A}$	$\phi$	$\tau$	$\omega$
$\tilde{\mathcal{E}} = +1$	1	0.1	0.05	1	0.05
$\tilde{\mathcal{E}} = -1$	0.8	0.08	0.05	1	0.05

$$\mathcal{A}^{\text{nr}} = 0.09$$

$$\mathcal{A}^{\mathcal{E}} = 0.01$$

$$\phi^{\text{nr}} = 0.05$$

$$\phi^{\mathcal{E}} = 0$$

$$\mathcal{C}^{\text{nr}} = 0.9$$

$$\mathcal{C}^{\mathcal{E}} = 0.1$$

$$\omega^{\text{nr}} = 0.05$$

$$\omega^{\mathcal{E}} = 0$$

$$\mathcal{A}_{\text{blinded}}^{\text{nr}} = 0.09$$

$$\mathcal{A}_{\text{blinded}}^{\mathcal{E}} = 0.01 + 0.01$$

$$\phi_{\text{blinded}}^{\text{nr}} = 0.05$$

$$\phi_{\text{blinded}}^{\mathcal{E}} = 0 + \frac{0.01}{2\mathcal{C}^{\text{nr}}}$$

$$\mathcal{C}_{\text{blinded}}^{\text{nr}} = 0.9$$

$$\mathcal{C}_{\text{blinded}}^{\mathcal{E}} = 0.1$$

$$\phi_{\text{blinded}}^{\mathcal{E}=+1} = 0.05 + \frac{0.01}{2\mathcal{C}^{\text{nr}}} = 0.05\dot{5}$$

$$\phi_{\text{blinded}}^{\mathcal{E}=-1} = 0.05 - \frac{0.01}{2\mathcal{C}^{\text{nr}}} = 0.04\dot{4}$$

	$\mathcal{C}_{\text{blinded}}$	$\mathcal{A}_{\text{blinded}}$	$\phi_{\text{blinded}}$ (from $\mathcal{A}_{\text{blinded}} / \phi_{\text{blinded}}$ )	$\tau_{\text{blinded}}$	$\omega_{\text{blinded}}$
$\tilde{\mathcal{E}} = +1$	1	0.11	0.055/0.05 $\dot{5}$	1	0.055/0.05 $\dot{5}$
$\tilde{\mathcal{E}} = -1$	0.8	0.07	0.04375/0.04 $\dot{4}$	1	0.04375/0.04 $\dot{4}$

This discrepancy reveals exactly how big the blind is

$$\mathcal{A}_{\text{blinded}}^{\text{nr}} = 0.09$$

$$\mathcal{A}_{\text{blinded}}^{\mathcal{E}} = 0.01 + 0.01$$

$$\phi_{\text{blinded}}^{\text{nr}} = 0.05$$

$$\phi_{\text{blinded}}^{\mathcal{E}} = 0 + \frac{0.01}{2\mathcal{C}^{\text{nr}}}$$

$$\mathcal{C}_{\text{blinded}}^{\text{nr}} = 0.9$$

$$\mathcal{C}_{\text{blinded}}^{\mathcal{E}} = 0.1$$

$$\phi_{\text{blinded}}^{\mathcal{E}=+1} = 0.05 + \frac{0.01}{2\mathcal{C}^{\text{nr}}} = 0.055$$

$$\phi_{\text{blinded}}^{\mathcal{E}=-1} = 0.05 - \frac{0.01}{2\mathcal{C}^{\text{nr}}} = 0.04375$$

	$\mathcal{C}_{\text{blinded}}$	$\mathcal{A}_{\text{blinded}}$	$\phi_{\text{blinded}}$ (from $\mathcal{A}_{\text{blinded}} / \phi_{\text{blinded}}$ )	$\tau_{\text{blinded}}$	$\omega_{\text{blinded}}$
$\tilde{\mathcal{E}} = +1$	1	0.11	0.055/0.055	1	0.055/0.055
$\tilde{\mathcal{E}} = -1$	0.8	0.07	0.04375/0.04375	1	0.04375/0.04375

This discrepancy reveals exactly how big the blind is

# “Inconsistent” blinding

- It was already known how to consistently blind in ACME II
- This consistent procedure was not chosen mostly to stay the same as ACME I. Also, it is arguably simpler conceptually.
- We propose changing the blinding procedure to this consistent procedure (applying blind in state basis looks equally simple conceptually)

**“Inconsistent” blinding  
(For phase)**



### 3 Example (issue with phase due to $\tau$ , exaggerated)

	$\phi^{\mathcal{N}\mathcal{E}}$	$\tau$	$\omega^{\mathcal{N}\mathcal{E}}$
$\tilde{\mathcal{P}} = +1$	1	1	1
$\tilde{\mathcal{P}} = -1$	3	3	1

1. Blind using average  $\tau = 2$  with  $\omega_{\text{blind}}^{\mathcal{N}\mathcal{E}} = 1$ :

$$\phi_{\tilde{\mathcal{P}}=+1}^{\mathcal{N}\mathcal{E}} = 1 \mapsto 1 + 1 * 2 = 3 \quad (4)$$

$$\phi_{\tilde{\mathcal{P}}=-1}^{\mathcal{N}\mathcal{E}} = 3 \mapsto 3 + 1 * 2 = 5, \quad (5)$$

and if we use this  $\phi$  to then compute  $\omega$ ,

$$\omega_{\tilde{\mathcal{P}}=+1}^{\mathcal{N}\mathcal{E}} = \phi_{\tilde{\mathcal{P}}=+1}^{\mathcal{N}\mathcal{E}} / \tau_{\tilde{\mathcal{P}}=+1} = 1 + 2 = 3 \quad (6)$$

$$\omega_{\tilde{\mathcal{P}}=-1}^{\mathcal{N}\mathcal{E}} = \phi_{\tilde{\mathcal{P}}=-1}^{\mathcal{N}\mathcal{E}} / \tau_{\tilde{\mathcal{P}}=+1} = 1 + 2/3 = 5/3. \quad (7)$$

The difference in effect of the applied blind basically reveal what the blind is since we know the value of  $\tau$ .

2. Blind using super-block state dependent  $\tau$  with  $\omega_{\text{blind}}^{\mathcal{N}\mathcal{E}} = 1$ :

$$\phi_{\mathcal{P}=+1}^{\mathcal{N}\mathcal{E}} = 1 \mapsto 1 + 1 * 1 = 2 \quad (8)$$

$$\phi_{\mathcal{P}=-1}^{\mathcal{N}\mathcal{E}} = 3 \mapsto 3 + 1 * 3 = 6, \quad (9)$$

Hence,  $\phi^{\mathcal{P}\mathcal{N}\mathcal{E}} = 1 \mapsto 2$ .

In summary, if one uses method [1](#) to blind, this is mathematically similar to the issue of having asymmetry and using the non-reversing contrast. The main difference here is that asymmetry becomes phase and non-reversing contrast becomes average  $\tau$ . The protocol is then: after blinding, one is not allowed to use phase to compute frequency. If one uses method [2](#) to blind, then one inevitably changes the values in the other parity channels, as it should be the case for state-by-state blinding.

Finding out the blind value  
when the blinded EDM is too  
big

## Story from ACME II...

In ACME II, the blinded value of the EDM is quite big (sorry I forgot how big). This basically immediately told us that the blinded EDM consists mostly of the blind value, thus revealing a lot of information about the blind. This was a possible concern.

But really, we should not worry about how much information is revealed about the blind, but instead about how much is revealed about the unblinded EDM value.

# Let us look at this more rigorously

We have random variables

1.  $E$ : value of the EDM, its distribution is somewhat arbitrary and describes one's belief about the real EDM value. Say it has pdf  $f(e)$
2.  $B$ : value of the blind, its distribution is defined by us. Say it has pdf  $g(b)$
3.  $Y \equiv E + B$ : sum of the EDM+blind visible by us. Its pdf is simply  $\int f(y - b)g(b)db$  as  $E, B$  are independent

To see how much information is revealed by looking at the blinded EDM, we look at the conditional pdf of  $E|Y$ ,

$$h_{E|Y}(e|y) = \frac{\text{pdf}_{E,Y}(e, y)}{\text{pdf}_Y(y)} = \frac{f(e)g(y - e)}{\int f(y - b)g(b)db}$$

Let's look at an example where pdfs of  $E, B$  are Gaussians given by

$$f(e) = \frac{1}{\sqrt{2\pi}\sigma_e} e^{-\frac{e^2}{2\sigma_e^2}}$$

$$g(b) = \frac{1}{\sqrt{2\pi}\sigma_b} e^{-\frac{b^2}{2\sigma_b^2}}$$

It is straightforward to evaluate the conditional distribution

$$h_{E|Y}(e|y) = \frac{\sqrt{\frac{1}{\sigma_e^2} + \frac{1}{\sigma_b^2}}}{2\pi} e^{-\frac{(y\sigma_e^2 - e(\sigma_b^2 + \sigma_e^2))^2}{2\sigma_b^2\sigma_e^2(\sigma_b^2 + \sigma_e^2)}}$$

This pdf is a Gaussian with mean  $\frac{y\sigma_e^2}{\sigma_b^2 + \sigma_e^2}$  and standard deviation  $\sqrt{\frac{\sigma_b^2\sigma_e^2}{\sigma_b^2 + \sigma_e^2}}$



